Package: workloopR (via r-universe)

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Type Package

Title Analysis of Work Loops and Other Data from Muscle Physiology Experiments

Version 1.1.4

Description Functions for the import, transformation, and analysis of data from muscle physiology experiments. The work loop technique is used to evaluate the mechanical work and power output of muscle. Josephson (1985) <doi:10.1242/jeb.114.1.493> modernized the technique for application in comparative biomechanics. Although our initial motivation was to provide functions to analyze work loop experiment data, as we developed the package we incorporated the ability to analyze data from experiments that are often complementary to work loops. There are currently three supported experiment types: work loops, simple twitches, and tetanus trials. Data can be imported directly from .ddf files or via an object constructor function. Through either method, data can then be cleaned or transformed via methods typically used in studies of muscle physiology. Data can then be analyzed to determine the timing and magnitude of force development and relaxation (for isometric trials) or the magnitude of work, net power, and instantaneous power among other things (for work loops). Although we do not provide plotting functions, all resultant objects are designed to be friendly to visualization via either base-R plotting or 'tidyverse' functions. This package has been peer-reviewed by rOpenSci (v. 1.1.0).

URL https://docs.ropensci.org/workloopR/,

https://github.com/ropensci/workloopR/

BugReports https://github.com/ropensci/workloopR/issues/

Imports pracma (>= 2.0.7), signal (>= 0.7-6)

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Contents

analyze_workloop	2
as_muscle_stim	5
fix_GR	7
get_wl_metadata	9
invert_position	0
isometric_timing	.1
read_analyze_wl	.3
read_analyze_wl_dir	5
read_ddf	7
read_ddf_dir	9
select_cycles	!1
summarize_wl_trials	!3
time_correct	!4
trapezoidal_integration	:6
2	28

Index

analyze_workloop *Analyze work loop object to compute work and power output*

Description

Compute work and power output from a work loop experiment on a per-cycle basis.

Usage

```
analyze_workloop(x, simplify = FALSE, GR = 1, M = -1, vel_bf = 0.05, ...)
```

Arguments

x	A workloop object of class muscle_stim that has been passed through select_cycles. See Details.
simplify	Logical. If FALSE, the full analyzed workloop object is returned. If TRUE a simpler table of net work and power (by cycle) is returned.
GR	Gear ratio, set to 1 by default

2

М	Velocity multiplier, set adjust the sign of velocity. This parameter should gener- ally be either -1 (the default) or 1.
vel_bf	Critical frequency (scalar) for low-pass filtering of velocity via signal::butter()
	Additional arguments potentially passed down from read_analyze_wl() or read_analyze_wl_dir()

Details

Please note that select_cycles() must be run on data prior to using this function. This function relies on the input muscle_stim object being organized by cycle number.

The muscle_stim object (x) must be a workloop, preferably read in by one of our data import functions. Please see documentation for as_muscle_stim() if you need to manually construct a muscle_stim object from a non .ddf source.

The gear ratio (GR) and velocity multiplier (M) parameters can help correct for issues related to the magnitude and sign of data collection. By default, they are set to apply no gear ratio adjustment and to positivize velocity. Instantaneous velocity is often noisy and the vel_bf parameter allows for low-pass filtering of velocity data. See signal::butter() and signal::filtfilt() for details of how filtering is achieved.

Please also be careful with units! Se Warning section below.

Value

The function returns a list of class analyzed_workloop that provides instantaneous velocity, a smoothed velocity, and computes work, instantaneous power, and net power from a work loop experiment. All data are organized by the cycle number and important metadata are stored as Attributes.

Within the list, each entry is labeled by cycle and includes:

Time	Time, in sec	
Position	Length change of the muscle, corrected for gear ratio, in mm	
Force	Force, corrected for gear ratio, in mN	
Stim	When stimulation occurs, on a binary scale	
Cycle	Cycle ID, as a letter	
<pre>Inst_velocity</pre>	$Instantaneous \ velocity, \ computed \ from \ {\tt Position} \ change, \ reported \ in \ meters/sec$	
Filt_velocity	Instantaneous velocity, after low-pass filtering, again in meter/sec	
Inst_Power	Instantaneous power, a product of Force and Filt_velocity, reported in J	
Percent_of_Cycle		
	The percent of that particular cycle which has elapsed	
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In addition, the following information is stored in the analyzed_workloop object's attributes:

stimulus_frequency

Frequency at which stimulus pulses occurred

cycle_frequency

Frequency of oscillations (assuming sine wave trajectory)

total_cycles	Total number of oscillatory cycles (assuming sine wave trajectory) that the mus-	
_ 3	cle experienced.	
cycle_def	Specifies what part of the cycle is understood as the beginning and end. There are currently three options: 'lo' for L0-to-L0; 'p2p' for peak-to-peak; and 't2t' for trough-to-trough	
amplitude	Amplitude of length change (assuming sine wave trajectory)	
phase	Phase of the oscillatory cycle (in percent) at which stimulation occurred. Some- what experimental, please use with caution	
position_inver	ted	
	Logical; whether position inversion has been applied)	
units	The units of measurement for each column in the object after running this func- tion. See Warning	
sample_frequent	cy	
	Frequency at which samples were collected	
header	Additional information from the header	
units_table	Units from each Channel of the original ddf file	
<pre>protocol_table</pre>	Protocol in tabular format; taken from the original ddf file	
stim_table	Specific info on stimulus protocol; taken from the original ddf file	
stimulus_pulses		
	Number of sequential pulses within a stimulation train	
stimulus_offset		
	Timing offset at which stimulus began	
gear_ratio	Gear ratio applied by this function	
file_id	File name	
mtime	Time at which file was last modified	
retained_cycles		
	Which cycles were retained, as numerics	
summary	Simple table showing work (in J) and net power (in W) for each cycle	

Warning

Most systems we have encountered record Position data in millimeters and Force in millinewtons, and therefore this function assumes data are recorded in those units. Through a series of internal conversions, this function computes velocity in meters/sec, work in Joules, and power in Watts. If your raw data do not originate in millimeters and millinewtons, please transform your data accordingly and ignore what you see in the attribute units.

Author(s)

Vikram B. Baliga and Shreeram Senthivasan

References

Josephson RK. 1985. Mechanical Power output from Striated Muscle during Cyclic Contraction. Journal of Experimental Biology 114: 493-512.

as_muscle_stim

See Also

read_ddf, read_analyze_wl, select_cycles

```
Other data analyses: isometric_timing(), read_analyze_wl_dir(), read_analyze_wl()
```

```
Other workloop functions: fix_GR(), get_wl_metadata(), invert_position(), read_analyze_wl_dir(),
read_analyze_wl(), select_cycles(), summarize_wl_trials(), time_correct()
```

Examples

library(workloopR)

```
# select cycles 3 through 5 via the peak-to-peak definition
wl_selected <- select_cycles(wl_dat, cycle_def = "p2p", keep_cycles = 3:5)</pre>
```

```
# run the analysis function and get the full object
wl_analyzed <- analyze_workloop(wl_selected, GR = 2)</pre>
```

print methods give a short summary
print(wl_analyzed)

```
# summary provides a bit more detail
summary(wl_analyzed)
```

```
# run the analysis but get the simplified version
wl_analyzed_simple <- analyze_workloop(wl_selected, simplify = TRUE, GR = 2)</pre>
```

as_muscle_stim Create your own muscle_stim object

Description

For use when data are not stored in .ddf format and you would like to create a muscle_stim object that can be used by other workloopR functions.

Usage

as_muscle_stim(x, type, sample_frequency, ...)

Arguments

х	A data.frame. See Details for how it should be organized.
type	Experiment type; must be one of: "workloop", "tetanus", or "twitch."

sample_frequency
Numeric value of the frequency at which samples were recorded; must be in Hz
Please format as numeric, e.g. 10000 works but 10000 Hz does not
Additional arguments that can be passed in as attributes. See Details.

Details

muscle_stim objects, which are required by (nearly) all workloopR functions, are automatically created via read_ddf(). Should you have data that are stored in a format other than .ddf, use this function to create your own object of class muscle_stim.

The input x must be a data.frame that contains time series of numeric data collected from an experiment. Each row must correspond to a sample, and these columns (exact title matches) must be included:

"Time" - time, recorded in seconds

"Position" - instantaneous position of the muscle, preferably in millimeters

"Force" - force, preferably in millinewtons

"Stim" - whether stimulation has occurred. All entries must be either 0 (no stimulus) or 1 (stimulus occurrence).

Additional arguments can be provided via For all experiment types, the following attributes are appropriate:

"units","header", "units_table", "protocol_table", "stim_table", "stimulus_pulses", "stimulus_offset", "stimulus_width", "gear_ratio", "file_id", or "mtime".

Please ensure that further attributes are appropriate to your experiment type.

For workloops, these include: "stimulus_frequency", "cycle_frequency", "total_cycles", "cycle_def", "amplitude", "phase", and "position_inverted"

For twitches or tetanic trials: "stimulus_frequency", and "stimulus_length"

Value

An object of class workloop, twitch, or tetanus, all of which inherit class muscle_stim. These objects behave like data.frames in most situations but also store metadata from the ddf as attributes.

The muscle_stim object's columns contain:

Time	Time	
Position	Length change of the muscle, uncorrected for gear ratio	
Force	Force, uncorrected for gear ratio	
Stim	When stimulation occurs, on a binary scale	
In addition, the following information is stored in the data.frame's attributes:		

sample_frequency Frequency at which samples were collected pulses Number of sequential pulses within a stimulation train total_cycles_lo Total number of oscillatory cycles (assuming sine wave trajectory) that the muscle experienced. Cycles are defined with respect to initial muscle length (L0-to-L0 as opposed to peak-to-peak).

fix_GR

amplitude	amplitude of length change (again, assuming sine wave trajectory)	
cycle_frequency		
	Frequency of oscillations (again, assuming sine wave trajectory)	
units	The units of measurement for each column in the data.frame. This might be the most important attribute so please check that it makes sense!	

Author(s)

Shreeram Senthivasan

See Also

read_ddf

```
Other data import functions: get_wl_metadata(), read_analyze_wl_dir(), read_analyze_wl(),
read_ddf_dir(), read_ddf()
```

Examples

library(workloopR)

fix_GR

Adjust for the gear ratio of a motor arm

Description

Fix a discrepancy between the gear ratio of the motor arm used and the gear ratio recorded by software.

Usage

 $fix_GR(x, GR = 1)$

Arguments

x	A muscle_stim object
GR	Gear ratio, set to 1 by default

Details

The muscle_stim object can be of any type, including workloop, twitch, or tetanus.

If you have manually constructed the object via as_muscle_stim(), the muscle_stim object should have columns as follows: Position: length change of the muscle;

Force: force

Value

An object of the same class(es) as the input (x). The function will multiply Position by (1/GR) and multiply Force by GR, returning an object with new values in \$Position and \$Force. Other columns and attributes are welcome and will simply be passed on unchanged into the resulting object.

Author(s)

Vikram B. Baliga

See Also

```
analyze_workloop, read_analyze_wl, read_analyze_wl_dir
```

Other data transformations: invert_position(), select_cycles()

Other workloop functions: analyze_workloop(), get_wl_metadata(), invert_position(), read_analyze_wl_dir(), read_analyze_wl(), select_cycles(), summarize_wl_trials(), time_correct()

Other twitch functions: invert_position(), isometric_timing()

Other tetanus functions: invert_position()

Examples

library(workloopR)

```
# apply a gear ratio correction of 2
# this will multiply Force by 2 and divide Position by 2
wl_fixed <- fix_GR(wl_dat, GR = 2)</pre>
```

```
# quick check:
max(wl_fixed$Force) / max(wl_dat$Force) # 5592.578 / 2796.289 = 2
max(wl_fixed$Position) / max(wl_dat$Position) # 1.832262 / 3.664524 = 0.5
```

get_wl_metadata

Description

Grab metadata from files stored in the same folder (e.g. a sequence of trials in an experiment).

Usage

```
get_wl_metadata(file_path, pattern = "*.ddf")
```

Arguments

file_path	Path where files are stored. Should be in the same folder.
pattern	Regex pattern for identifying relevant files in the file_path.

Details

If several files (e.g. successive trials from one experiment) are stored in one folder, use this function to obtain metadata in a list format. Runs file.info() from base R to extract info from files.

This function is not truly considered to be part of the batch analysis pipeline; see read_analyze_wl_dir() for a similar function that not only grabs metadata but also imports & analyzes files. Instead, get_wl_metadata() is meant to be a handy function to investigate metadata issues that arise if running read_analyze_wl_dir() goes awry.

Unlike read_analyze_wl_dir(), this function does not necessarily need files to all be work loops. Any file type is welcome (as long as the Regex pattern argument makes sense).

Value

Either a data.frame (if a single file is supplied) or a list of data.frames (if a list of files is supplied), with information as supplied from file.info().

Author(s)

Vikram B. Baliga

See Also

summarize_wl_trials

Other data import functions: as_muscle_stim(), read_analyze_wl_dir(), read_analyze_wl(), read_ddf_dir(), read_ddf()

Other workloop functions: analyze_workloop(), fix_GR(), invert_position(), read_analyze_wl_dir(), read_analyze_wl(), select_cycles(), summarize_wl_trials(), time_correct()

Other batch analyses: read_analyze_wl_dir(), summarize_wl_trials(), time_correct()

Examples

library(workloopR)

invert_position Invert the position data

Description

Multiply instantaneous position by -1.

Usage

invert_position(x)

Arguments

х

A muscle_stim object

Details

The muscle_stim object can be of any type, including workloop, twitch, or tetanus.

If you have manually constructed the object via as_muscle_stim(), the muscle_stim object should have a column entitled Position. Other columns and attributes are welcome and will be passed along unchanged.

Value

A workloop object with inverted position. The position_inverted attribute is set to TRUE and all others are retained.

Author(s)

Vikram B. Baliga

See Also

Other data transformations: fix_GR(), select_cycles()

Other workloop functions: analyze_workloop(), fix_GR(), get_wl_metadata(), read_analyze_wl_dir(), read_analyze_wl(), select_cycles(), summarize_wl_trials(), time_correct()

Other twitch functions: fix_GR(), isometric_timing()

Other tetanus functions: fix_GR()

10

isometric_timing

Examples

library(workloopR)

invert the sign of Position

```
wl_fixed <- invert_position(wl_dat)
# quick check:</pre>
```

```
max(wl_fixed$Position) / min(wl_dat$Position) # -1
```

isometric_timing Compute timing and magnitude of force in isometric trials

Description

Calculate timing and magnitude of force at stimulation, peak force, and various parts of the rising (force development) and relaxation (falling) phases of the twitch.

Usage

```
isometric\_timing(x, rising = c(10, 90), relaxing = c(90, 50))
```

Arguments

х	A muscle_stim object that contains data from an isometric twitch trial, ideally created via read_ddf.
rising	Set points of the rising phase to be described. By default: 10% and 90%.
relaxing	Set points of the relaxation phase to be described. By default: 90% and 50%.

Details

The data.frame (x) must have time series data organized in columns. Generally, it is preferred that you use a muscle_stim object imported by read_ddf().

The rising and relaxing arguments allow for the user to supply numeric vectors of any length. By default, these arguments are rising = c(10, 90) and relaxing = c(90, 50). Numbers in each of these correspond to percent values and capture time and force at that percent of the corresponding curve. These values can be replaced by those that the user specifies and do not necessarily need to have length = 2. But please note that 0 and 100 should not be used, e.g. rising = seq(10, 90, 5) works, but rising = seq(0, 100, 5) does not.

Value

A data.frame with the following metrics as columns:

file_ID	File ID	
time_stim	Time between beginning of data collection and when stimulation occurs	
force_stim	Magnitude of force at the onset of stimulation	
time_peak	Absolute time of peak force, i.e. time between beginning of data collection and when peak force occurs	
force_peak	Magnitude of peak force	
time_rising_X	Time between beginning of data collection and X% of force development	
<pre>force_rising_X</pre>	Magnitude of force at X% of force development	
<pre>time_relaxing_X</pre>		
	Time between beginning of data collection and X% of force relaxation	
force_relaxing_	Х	
	Magnitude of force at X% of relaxation	

Author(s)

Vikram B. Baliga

References

Ahn AN, and Full RJ. 2002. A motor and a brake: two leg extensor muscles acting at the same joint manage energy differently in a running insect. Journal of Experimental Biology 205, 379-389.

See Also

Other data analyses: analyze_workloop(), read_analyze_wl_dir(), read_analyze_wl() Other twitch functions: fix_GR(), invert_position()

Examples

library(workloopR)

read_analyze_wl All-in-one import function for work loop files

Description

read_analyze_wl() is an all-in-one function to read in a work loop file, select cycles, and compute work and power output.

Usage

```
read_analyze_wl(file_name, ...)
```

Arguments

file_name	A .ddf file that contains data from a single workloop experiment
	Additional arguments to be passed to read_ddf(), select_cycles(), or analyze_workloop().

Details

Please be careful with units! See Warnings below. This function combines read_ddf() with select_cycles() and then ultimately analyze_workloop() into one handy function.

As detailed in these three functions, possible arguments include:

cycle_def - used to specify which part of the cycle is understood as the beginning and end. There are currently three options: 'lo' for L0-to-L0; 'p2p' for peak-to-peak; and 't2t' for trough-to-trough bworth_order - Filter order for low-pass filtering of Position via signal::butter prior to finding peak lengths. Default: 2.

bworth_freq - Critical frequency (scalar) for low-pass filtering of Position via signal::butter prior to finding peak lengths. Default: 0.05.

keep_cycles - Which cycles should be retained. Default: 4:6.

GR - Gear ratio. Default: 1.

M - Velocity multiplier used to positivize velocity; should be either -1 or 1. Default: -1.

vel_bf - Critical frequency (scalar) for low-pass filtering of velocity via signal::butter. Default: 0.05.

The gear ratio (GR) and velocity multiplier (M) parameters can help correct for issues related to the magnitude and sign of data collection. By default, they are set to apply no gear ratio adjustment and to positivize velocity. Instantaneous velocity is often noisy and the vel_bf parameter allows for low-pass filtering of velocity data. See signal::butter() and signal::filtfilt() for details of how filtering is achieved.

Value

The function returns a list of class analyzed_workloop that provides instantaneous velocity, a smoothed velocity, and computes work, instantaneous power, and net power from a work loop experiment. All data are organized by the cycle number and important metadata are stored as Attributes.

Within the list, each entry is labeled by cycle and includes:

Time	Time, in sec	
Position	Length change of the muscle, corrected for gear ratio, in mm	
Force	Force, corrected for gear ratio, in mN	
Stim	When stimulation occurs, on a binary scale	
Cycle	Cycle ID, as a letter	
Inst_velocity	Instantaneous velocity, computed from Position change, reported in meters/sec	
Filt_velocity	Instantaneous velocity, after low-pass filtering, again in meter/sec	
Inst_Power	Instantaneous power, a product of Force and Filt_velocity, reported in J	
Percent_of_Cyc	le	
	The percent of that particular cycle which has elapsed	
In addition, the fo	llowing information is stored in the analyzed_workloop object's attributes:	
stimulus_freque	ency	
	Frequency at which stimulus pulses occurred	
cycle_frequency		
	Frequency of oscillations (assuming sine wave trajectory)	
total_cycles	Total number of oscillatory cycles (assuming sine wave trajectory) that the mus- cle experienced.	
cycle_def	Specifies what part of the cycle is understood as the beginning and end. There are currently three options: 'lo' for L0-to-L0; 'p2p' for peak-to-peak; and 't2t' for trough-to-trough	
amplitude	Amplitude of length change (assuming sine wave trajectory)	
phase	Phase of the oscillatory cycle (in percent) at which stimulation occurred. Some- what experimental, please use with caution	
position_inverted		
	Logical; whether position inversion has been applied)	
units	The units of measurement for each column in the object after running this func- tion. See Warning	
sample_frequent		
	Frequency at which samples were collected	
header	Additional information from the header	
units_table	Units from each Channel of the original ddf file	
	Protocol in tabular format; taken from the original ddf file	
<pre>stim_table Specific info on stimulus protocol; taken from the original ddf file stimulus_pulses</pre>		
Number of sequential pulses within a stimulation train		
stimulus_offse		
	Timing offset at which stimulus began	
gear_ratio	Gear ratio applied by this function	
file_id	File name	
<pre>mtime retained_cycles</pre>		
	Which cycles were retained, as numerics	
summary	Simple table showing work (in J) and net power (in W) for each cycle	

Warning

Most systems we have encountered record Position data in millimeters and Force in millinewtons, and therefore this function assumes data are recorded in those units. Through a series of internal conversions, this function computes velocity in meters/sec, work in Joules, and power in Watts. If your raw data do not originate in millimeters and millinewtons, please transform your data accordingly and ignore what you see in the attribute units.

Author(s)

Vikram B. Baliga

References

Josephson RK. 1985. Mechanical Power output from Striated Muscle during Cyclic Contraction. Journal of Experimental Biology 114: 493-512.

See Also

read_ddf, select_cycles analyze_workloop

Other data analyses: analyze_workloop(), isometric_timing(), read_analyze_wl_dir()

Other data import functions: as_muscle_stim(), get_wl_metadata(), read_analyze_wl_dir(), read_ddf_dir(), read_ddf()

Other workloop functions: analyze_workloop(), fix_GR(), get_wl_metadata(), invert_position(), read_analyze_wl_dir(), select_cycles(), summarize_wl_trials(), time_correct()

Examples

library(workloopR)

read_analyze_wl_dir Read and analyze work loop files from a directory

Description

All-in-one function to import multiple workloop .ddf files from a directory, sort them by mtime, analyze them, and store the resulting objects in an ordered list.

Usage

```
read_analyze_wl_dir(file_path, pattern = "*.ddf", sort_by = "mtime", ...)
```

Arguments

file_path	Directory in which files are located
pattern	Regular expression used to specify files of interest. Defaults to all .ddf files within file_path
sort_by	Metadata by which files should be sorted to be in the correct run order. Defaults to mtime, which is time of last modification of files.
	Additional arguments to be passed to read_analyze_wl(), analyze_workloop(), select_cycles(), or read_ddf().

Details

Work loop data files will be imported and then arranged in the order in which they were run (assuming run order is reflected in mtime). Chiefly used in conjunction with summarize_wl_trials() and time_correct() if time correction is desired.

Value

A list containing analyzed_workloop objects, one for each file that is imported and subsequently analyzed. The list is sorted according to the sort_by parameter, which by default uses the time of last modification of each file's contents (mtime).

Warning

Most systems we have encountered record Position data in millimeters and Force in millinewtons, and therefore this function assumes data are recorded in those units. Through a series of internal conversions, this function computes velocity in meters/sec, work in Joules, and power in Watts. If your raw data do not originate in millimeters and millinewtons, please transform your data accordingly and ignore what you see in the attribute units.

Author(s)

Shreeram Senthivasan

References

Josephson RK. 1985. Mechanical Power output from Striated Muscle during Cyclic Contraction. Journal of Experimental Biology 114: 493-512.

See Also

read_analyze_wl, get_wl_metadata, summarize_wl_trials, time_correct

Other data analyses: analyze_workloop(), isometric_timing(), read_analyze_wl()

Other data import functions: as_muscle_stim(), get_wl_metadata(), read_analyze_wl(), read_ddf_dir(), read_ddf()

read_ddf

Other workloop functions: analyze_workloop(), fix_GR(), get_wl_metadata(), invert_position(), read_analyze_wl(), select_cycles(), summarize_wl_trials(), time_correct()

Other batch analyses: get_wl_metadata(), summarize_wl_trials(), time_correct()

Examples

library(workloopR)

read_ddf

Import work loop or isometric data from .ddf files

Description

read_ddf reads in workloop, twitch, or tetanus experiment data from .ddf files.

Usage

```
read_ddf(
   file_name,
   file_id = NA,
   rename_cols = list(c(2, 3), c("Position", "Force")),
   skip_cols = 4:11,
   phase_from_peak = FALSE,
   ...
)
```

Arguments

file_name	A .ddf file that contains data from a single workloop, twitch, or tetanus experiment	
file_id	A string identifying the experiment. The file name is used by default.	
rename_cols	List consisting of a vector of indices of columns to rename and a vector of new column names. See Details.	
skip_cols	Numeric vector of column indices to skip. See Details.	
phase_from_peak		
	Logical, indicating whether percent phase of stimulation should be recorded relative to peak length or relative to L0 (default)	
	Additional arguments passed to/from other functions that work with read_ddf()	

Details

Read in a .ddf file that contains data from an experiment. If position and force do not correspond to columns 2 and 3 (respectively), replace "2" and "3" within rename_cols accordingly. Similarly, skip_cols = 4:11 should be adjusted if more than 11 columns are present and/or columns 4:11 contain important data.

Please note that there is no correction for gear ratio or further manipulation of data. See fix_GR to adjust gear ratio. Gear ratio can also be adjusted prior to analyses within the analyze_workloop() function, the data import all-in-one function read_analyze_wl(), or the batch analysis all-in-one read_analyze_wl_dir().

Please also note that organization of data within the .ddf file is assumed to conform to that used by Aurora Scientific's Dynamic Muscle Control and Analysis Software. YMMV if using a .ddf file from another source. The as_muscle_stim() function can be used to generate muscle_stim objects if data are imported via another function. Please feel free to contact us with any issues or requests.

Value

An object of class workloop, twitch, or tetanus, all of which inherit class muscle_stim. These objects behave like data.frames in most situations but also store metadata from the ddf as attributes.

The muscle_stim object's columns contain:

Time	Time	
Position	Length change of the muscle, uncorrected for gear ratio	
Force	Force, uncorrected for gear ratio	
Stim	When stimulation occurs, on a binary scale	
In addition, the following information is stored in the data.frame's attributes:		
sample_frequency		
	Frequency at which samples were collected	
pulses	Number of sequential pulses within a stimulation train	
total_cycles_lo		
	Total number of oscillatory cycles (assuming sine wave trajectory) that the mus- cle experienced. Cycles are defined with respect to initial muscle length (L0-to- L0 as opposed to peak-to-peak).	
amplitude	amplitude of length change (again, assuming sine wave trajectory)	
cycle_frequency		
	Frequency of oscillations (again, assuming sine wave trajectory)	
units	The units of measurement for each column in the data.frame. This might be the most important attribute so please check that it makes sense!	

Author(s)

Vikram B. Baliga and Shreeram Senthivasan

18

read_ddf_dir

See Also

Other data import functions: as_muscle_stim(), get_wl_metadata(), read_analyze_wl_dir(), read_analyze_wl(), read_ddf_dir()

Examples

library(workloopR)

read_ddf_dir Import a batch of work loop or isometric data files from a directory

Description

Uses read_ddf() to read in workloop, twitch, or tetanus experiment data from multiple .ddf files.

Usage

```
read_ddf_dir(file_path, pattern = "*.ddf", sort_by = "mtime", ...)
```

Arguments

file_path	Path where files are stored. Should be in the same folder.
pattern	Regex pattern for identifying relevant files in the file_path.
sort_by	Metadata by which files should be sorted to be in the correct run order. Defaults to mtime, which is time of last modification of files.
	Additional arguments to be passed to read_ddf().

Details

Read in a .ddf file that contains data from an experiment. If position and force do not correspond to columns 2 and 3 (respectively), replace "2" and "3" within rename_cols accordingly. Similarly, skip_cols = 4:11 should be adjusted if more than 11 columns are present and/or columns 4:11 contain important data.

Please note that there is no correction for gear ratio or further manipulation of data. See fix_GR to adjust gear ratio. Gear ratio can also be adjusted prior to analyses within the analyze_workloop() function, the data import all-in-one function read_analyze_wl(), or the batch analysis all-in-one read_analyze_wl_dir().

Please also note that organization of data within the .ddf file is assumed to conform to that used by Aurora Scientific's Dynamic Muscle Control and Analysis Software. YMMV if using a .ddf

file from another source. The as_muscle_stim() function can be used to generate muscle_stim objects if data are imported via another function. Please feel free to contact us with any issues or requests.

Value

A list of objects of class workloop, twitch, or tetanus, all of which inherit class muscle_stim. These objects behave like data.frames in most situations but also store metadata from the ddf as attributes.

Each muscle_stim object's columns contain:

Time	Time	
Position	Length change of the muscle, uncorrected for gear ratio	
Force	Force, uncorrected for gear ratio	
Stim	When stimulation occurs, on a binary scale	
In addition, the fol	lowing information is stored in each data.frame's attributes:	
sample_frequenc	у	
	Frequency at which samples were collected	
pulses	Number of sequential pulses within a stimulation train	
total_cycles_lo		
	Total number of oscillatory cycles (assuming sine wave trajectory) that the mus- cle experienced. Cycles are defined with respect to initial muscle length (L0-to- L0 as opposed to peak-to-peak).	
amplitude	amplitude of length change (again, assuming sine wave trajectory)	
cycle_frequency		
	Frequency of oscillations (again, assuming sine wave trajectory)	
units	The units of measurement for each column in the data.frame. This might be the most important attribute so please check that it makes sense!	

Author(s)

Vikram B. Baliga and Shreeram Senthivasan

See Also

```
Other data import functions: as_muscle_stim(), get_wl_metadata(), read_analyze_wl_dir(),
read_analyze_wl(), read_ddf()
```

Examples

```
library(workloopR)
```

select_cycles

Description

Retain data from a work loop experiment based on position cycle

Usage

```
select_cycles(
    x,
    cycle_def,
    keep_cycles = 4:6,
    bworth_order = 2,
    bworth_freq = 0.05,
    ...
)
```

Arguments

Х	A workloop object (see Details for how it should be organized)	
cycle_def	A string specifying how cycles should be defined; one of: "lo", "p2p", or "t2t". See Details more info	
keep_cycles	The indices of the cycles to keep. Include 0 to keep data identified as being outside complete cycles	
bworth_order	Filter order for low-pass filtering of Position via signal::butter() prior to finding L0 $$	
bworth_freq	Critical frequency (scalar) for low-pass filtering of Position via signal::butter() prior to finding L0 $$	
	Additional arguments passed to/from other functions that make use of select_cycles()	

Details

select_cycles() subsets data from a workloop trial by position cycle. The cycle_def argument is used to specify which part of the cycle is understood as the beginning and end. There are currently three options: 'lo' for L0-to-L0; 'p2p' for peak-to-peak; and 't2t' for trough-to-trough

Peaks are identified using pracma::findpeaks(). L0 points on the rising edge are found by finding the midpoints between troughs and the following peak. However the first and last extrema and L0 points may be misidentified by this method. Please plot your Position cycles to ensure the edge cases are identified correctly.

The keep_cycles argument is used to determine which cycles (as defined by cycle_def should be retained in the final dataset. Zero is the index assigned to all data points that are determined to be outside a complete cycle.

The muscle_stim object (x) must be a workloop, preferably read in by one of our data import functions. Please see documentation for as_muscle_stim() if you need to manually construct a muscle_stim object from another source.

Value

A workloop object with rows subsetted by the chosen position cycles. A Cycle column is appended to denote which cycle each time point is associated with. Finally, all attributes from the input workloop object are retained and one new attribute is added to record which cycles from the original data were retained.

Author(s)

Vikram B. Baliga and Shreeram Senthivasan

See Also

analyze_workloop, read_analyze_wl, read_analyze_wl_dir

Other data transformations: fix_GR(), invert_position()

Other workloop functions: analyze_workloop(), fix_GR(), get_wl_metadata(), invert_position(), read_analyze_wl_dir(), read_analyze_wl(), summarize_wl_trials(), time_correct()

Examples

library(workloopR)

select cycles 3 through 5 via the peak-to-peak definition
wl_selected <- select_cycles(wl_dat, cycle_def = "p2p", keep_cycles = 3:5)</pre>

```
# are the cycles of (approximately) the same length?
summary(as.factor(wl_selected$Cycle))
```

summarize_wl_trials Summarize work loop files

Description

Summarize important info from work loop files stored in the same folder (e.g. a sequence of trials in an experiment) including experimental parameters, run order, and mtime.

Usage

```
summarize_wl_trials(wl_list)
```

Arguments

wl_list List of analyzed_workloop objects, preferably one created by read_analyze_wl_dir().

Details

If several files (e.g. successive trials from one experiment) are stored in one folder, use this function to obtain summary stats and metadata and other parameters. This function requires a list of analyze_workloop objects, which can be readily obtained by first running read_analyze_wl_dir() on a specified directory.

Value

A data.frame of information about the collection of workloop files. Columns include:

File_ID	Name of the file	
Cycle_Frequency		
	Frequency of Position change	
Amplitude	amplitude of Position change	
Phase	Phase of the oscillatory cycle (in percent) at which stimulation occurred. Some- what experimental, please use with caution	
Stimulus_Pulses		
	Number of stimulation pulses	
mtime	Time at which file's contents were last changed (mtime)	
Mean_Work	Mean work output from the selected cycles	
Mean_Power	Net power output from the selected cycles	

Author(s)

Vikram B. Baliga and Shreeram Senthivasan

References

Josephson RK. 1985. Mechanical Power output from Striated Muscle during Cyclic Contraction. Journal of Experimental Biology 114: 493-512.

See Also

read_analyze_wl_dir, get_wl_metadata, time_correct

Other workloop functions: analyze_workloop(), fix_GR(), get_wl_metadata(), invert_position(), read_analyze_wl_dir(), read_analyze_wl(), select_cycles(), time_correct()

Other batch analyses: get_wl_metadata(), read_analyze_wl_dir(), time_correct()

Examples

library(workloopR)

```
summarized_wls <- summarize_wl_trials(analyzed_wls)</pre>
```

time_correct Time correction for work loop experiments

Description

Correct for potential degradation of muscle over time.

Usage

time_correct(x)

Arguments

Х

A data.frame with summary data, e.g. an object created by summarize_wl_trials().

Details

This function assumes that across a batch of successive trials, the stimulation parameters for the first and final trials are identical. If not, DO NOT USE. Decline in power output is therefore assumed to be a linear function of time. Accordingly, the difference between the final and first trial's (absolute) power output is used to 'correct' trials that occur in between, with explicit consideration of run order and time elapsed (via mtime). A similar correction procedure is applied to work.

24

time_correct

Value

A data. frame that additionally contains:

Time_Corrected_Work

Time corrected work output, transformed from \$Mean_Work

Time_Corrected_Power

Time corrected net power output, transformed from \$Mean_Power

And new attributes: power_difference Difference in mass-specific net power output between the final and first trials. time_difference Difference in mtime between the final and first trials. time_correction_rate Overall rate; power_difference divided by time_difference.

Author(s)

Vikram B. Baliga and Shreeram Senthivasan

See Also

summarize_wl_trials

```
Other workloop functions: analyze_workloop(), fix_GR(), get_wl_metadata(), invert_position(),
read_analyze_wl_dir(), read_analyze_wl(), select_cycles(), summarize_wl_trials()
Other batch analyses: get_wl_metadata(), read_analyze_wl_dir(), summarize_wl_trials()
```

Examples

library(workloopR)

timecor_wls <- time_correct(summarized_wls)</pre>

timecor_wls

trapezoidal_integration

Approximate the definite integral via the trapezoidal rule

Description

Mostly meant for internal use in our analysis functions, but made available for other use cases. Accordingly, it does not strictly rely on objects of class muscle_stim.

Usage

```
trapezoidal_integration(x, f)
```

Arguments

х	a variable, e.g. vector of positions
f	integrand, e.g. vector of forces

Details

In the functions analyze_workloop(), read_analyze_wl(), and read_analyze_wl_dir(), work is calculated as the difference between the integral of the upper curve and the integral of the lower curve of a work loop.

Value

A numerical value indicating the value of the integral.

Author(s)

Vikram B. Baliga

References

Atkinson, Kendall E. (1989), An Introduction to Numerical Analysis (2nd ed.), New York: John Wiley & Sons

See Also

analyze_workloop, read_analyze_wl, read_analyze_wl_dir

Examples

```
# create a circle centered at (x = 10, y = 20) with radius 2
t <- seq(0, 2 * pi, length = 1000)
coords <- t(rbind(10 + sin(t) * 2, 20 + cos(t) * 2))</pre>
```

```
# use the function to get the area
trapezoidal_integration(coords[, 1], coords[, 2])
```

```
# does it match (pi * r^2)?
3.14159265358 * (2^2) # very close
```

Index

* batch analyses get_wl_metadata,9 read_analyze_wl_dir, 15 summarize_wl_trials, 23 time_correct, 24 * data analyses analyze_workloop, 2 isometric_timing, 11 read_analyze_wl, 13 read_analyze_wl_dir, 15 * data import functions as_muscle_stim, 5 get_wl_metadata, 9 read_analyze_wl, 13 read_analyze_wl_dir, 15 read_ddf, 17 read_ddf_dir, 19 * data transformations fix_GR,7 invert_position, 10 select_cycles, 21 *** tetanus functions** fix GR.7 invert_position, 10 * twitch functions fix_GR,7 invert_position, 10 isometric_timing, 11 * workloop functions analyze_workloop, 2 fix_GR,7 get_wl_metadata, 9 invert_position, 10 read_analyze_wl, 13 read_analyze_wl_dir, 15 select_cycles, 21 summarize_wl_trials, 23 time_correct, 24

24 - 26as_muscle_stim, 5, 9, 15, 16, 19, 20 fix_GR, 5, 7, 9, 10, 12, 15, 17, 22, 24, 25 get_wl_metadata, 5, 7, 8, 9, 10, 15-17, 19, 20, 22, 24, 25 invert_position, 5, 8, 9, 10, 12, 15, 17, 22, 24, 25 isometric_timing, 5, 8, 10, 11, 15, 16 read_analyze_wl, 5, 7-10, 12, 13, 16, 17, 19, 20, 22, 24-26 read_analyze_wl_dir, 5, 7-10, 12, 15, 15, 19, 20, 22, 24-26 read_ddf, 5, 7, 9, 15, 16, 17, 20 read_ddf_dir, 7, 9, 15, 16, 19, 19 select_cycles, 5, 8-10, 15, 17, 21, 24, 25 summarize_wl_trials, 5, 8-10, 15-17, 22, 23, 25

time_correct, *5*, *8–10*, *15–17*, *22*, *24*, 24 trapezoidal_integration, 26

analyze_workloop, 2, 8-10, 12, 15-17, 22,